

# Automatic Adaptation of the Computing Precision

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# Context

My field: interval arithmetic and arbitrary precision.

## Recurring problems:

- ▶ how to detect that the current computing precision does not suffice?
- ▶ how to increase the current computing precision?

**Today's problem:** how to increase the current computing precision?

# Ideally...

Let the exact solution of a given problem be  $x^*$ .

**Goal:** compute an approximation  $\tilde{x}$  of the exact solution  $x^*$  with prescribed accuracy:

$$|\tilde{x} - x^*| \leq \epsilon.$$

The optimal computing precision to reach this accuracy is  $p^*$ .

## In the real world...

Let the exact solution of a given problem be  $x^*$ .

**Goal:** compute an approximation  $\tilde{x}$  of the exact solution  $x^*$  with prescribed accuracy:

$$|\tilde{x} - x^*| \leq \epsilon.$$

The optimal computing precision to reach this accuracy is  $p^*$  but  $p^*$  is unknown.

### Method:

- ▶ try to compute with a precision  $p_0$
- ▶ if the result is not accurate enough, change the precision to  $p_1$   
try to compute with the precision  $p_1$
- ▶ try with precisions  $p_2 \dots p_i \dots p_n$   
until the precision  $p_n \geq p^*$ .

# Assumptions

Let  $\tilde{x}(p)$  be the approximation computed with precision  $p$ .

Let  $\varepsilon(p)$  be the accuracy:  $|\tilde{x}(p) - x^*| \leq \varepsilon(p)$ .

$$\varepsilon(p) \rightarrow 0 \text{ as } p \rightarrow +\infty.$$

# Notations

Optimal precision  $p^*$

Computing time  $t^*$

---

precision  $p_0$

computing time  $t_0$

precision  $p_1$

computing time  $t_1$

$\vdots$

$\vdots$

precision  $p_n$

computing time  $t_n$

---

finally  $p_n \geq p^*$  total computing time  $T = \sum_{i=0}^n t_i$

overhead =  $T/t^*$

# Question

## How to minimize the overhead?

In other words, if  $p_i$  is not large enough,  
how should we choose  $p_{i+1}$ ?

# Motivation

**Theoretical results exist. . .  
but practical experiments + intuition contradict these  
results!**



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**Theoretical results exist. . .  
but practical experiments + intuition contradict these  
results!**

Approach:

- ▶ survey existing work
- ▶ analyse the theoretical result to determine where and when we disagree.

# Outline

Problem

Experimental and theoretical results

Implementations

Theoretical results

New results

Assumptions and new results

Asymptotically optimal results

Conclusion and future work

# iRRAM

## Müller 2000, based on Brattka and Hertling 1995

*It is well-known that the asymptotic complexity of sequences of iterated computations is of the same order as the complexity of the last iteration.*

Choice of the new precision:

$$p_i = p_0 + g \frac{f^i - 1}{f - 1}, \text{ with } g = 50 \text{ and } f = 1.25.$$

or equivalently

$$p_i - p_0 = g + f \cdot (p_{i-1} - p_0).$$

*the precision bound is incremented as above, the computation is restarted from the beginning.*

# Mathemagix

van der Hoeven 2006

*Then we let  $p_{i+1} > p_i$  be such that  $t_{i+1} \simeq 2t_i$  and we replace our  $p_i$ -digit approximation by a  $p_{i+1}$ -digit approximation.*

*[...]*

*Consequently the total time is approximately twice the time of the last iteration and less than 4 times the optimal time.*

*More generally, the evaluation at different precisions  $p_1, \dots, p_n$  requires at most four times the evaluation at the maximal precision  $\max(p_1, \dots, p_n)$ .*

# MPFR

Fousse, Hanrot, Lefèvre, Pélissier, Théveny, Zimmermann et al.

**In theory:** increase the precision to be able to round correctly  
take into account the probability of failure  
increment the current precision  $p$  by  $\log p$   
average of the overhead OK: large overheads are very unlikely

## **In practice:**

first iteration: just add one extra-word

next iterations: precision is a geometric series of ratio 1.5

# Interval Newton using MPFI

Revol 2003

## Context:

determine the zeros of a function with a prescribed accuracy using interval Newton and a given precision.

## Adaptation of the computing precision:

if the accuracy is not reached,

**double** the precision

since the result will be twice more accurate.

No mention neither of the computing time nor of the overhead.

## Reminder: Notations

Optimal precision  $p^*$

Computing time  $t^*$

---

precision  $p_0$

computing time  $t_0$

precision  $p_1$

computing time  $t_1$

$\vdots$

$\vdots$

precision  $p_n$

computing time  $t_n$

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finally  $p_n \geq p^*$  total computing time  $T = \sum_{i=0}^n t_i$

overhead =  $T/t^*$

# Theoretical results

## Kreinovich and Rump, 2006

### Result 1:

**if** precision  $p_i$  so that  $t_i = 2t_{i-1}$

**then** overhead = 4.

Furthermore: 4 is the minimal overhead for every geometric sequence of  $(t_i)$ .

### Result 2:

for every increasing sequence of  $(t_i)$ ,

**if** the total time is  $T = \sum_{i=0}^n t_i$

**then** overhead  $\geq 4$ .



# Questions

- ▶ Is this optimal result really optimal
- ▶ Can the overhead be  $< 4$ ?
- ▶ Can the overhead be only 2 for Newton?
- ▶ Can the overhead be even less?

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# Assumptions

The new iteration can benefit from the previous computations, instead of being restarted from scratch.

## Typical example: Newton

Starting from the last iterate and doubling the computing precision yields a result with twice the precision of the last iterate.

$$\begin{array}{r}
 t^* = t_0^* + t_1^* + \dots + t_i^* + t_{i+1}^* + \dots + t_n^* \\
 T = \phantom{t^* = } \phantom{t_0^* + } \phantom{t_1^* + } \phantom{\dots + } t_0 + t_1 + \dots + t_{n-1} + t_n
 \end{array}$$

**Overhead**  $\leq 1 + t_n/t^*$ .

## Example of Newton with time linear in the precision

Example: if  $t_i = c.p_i^*$  and  $p_i^* = 2p_{i-1}^*$ ,  
 optimal time  $t^* = \sum_{i=0}^n c.p_i^* = \sum_{i=0}^n c.p^*/2^i = 2.c.p^*$ :  
 time of the last iteration = time of all previous iterations.

If  $p^*$  is not known,  
 iterations with precisions  $p_0, p_1, \dots, p_{n-1} < p^*, p_n \geq p^*$ .  
 At worst  $p_n \simeq 2p^*$ ,  
 time for this extra-iteration = time of all previous iterations  $\simeq$   
 optimal time.

**In conclusion**, total time  $\simeq 2$  optimal time  
 i.e. **overhead**  $\leq 2$ .

# Notations

## Ideal world

precision  $p_0^*$   
 precision  $p_1^*$   
 $\vdots$   
 precision  $p_m^*$

time  $t_0^*$   
 time  $t_1^*$   
 $\vdots$   
 time  $t_m^*$

$$p^* := p_m^* \quad \text{total computing time } T^* = \sum_{i=0}^m t_i^*$$

## Real world

precision  $p_0$   
 precision  $p_1$   
 $\vdots$   
 precision  $p_n$

computing time  $t_0$   
 computing time  $t_1$   
 $\vdots$   
 computing time  $t_n$

$$\text{finally } p_n \geq p^* \quad \text{total computing time } T = \sum_{i=0}^n t_i$$

$$\text{overhead} = T/T^*$$

# Simplifying Assumptions

Computing times are proportional to the computing precision:

$$t = p.$$

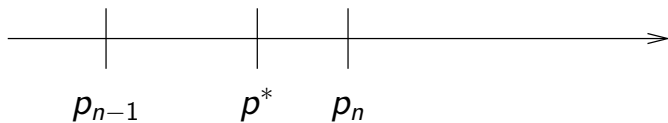
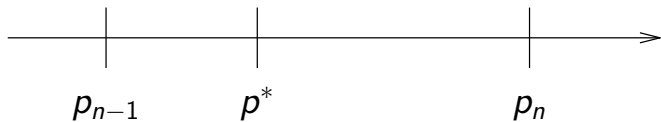
Precisions are equal except the last one:

$$p_0 = p_0^*, p_1 = p_1^*, \dots, p_{n-1} < p_m^* \leq p_n.$$

Thus

$$T - T^* = t_n - t^* \leq t_n - t_{n-1}.$$

## Important point



# Asymptotically optimal results

**Idea:** inspired from amortized techniques by Floyd and Brent adapted from [Beaumont, Daoudi, Maillard, Manneback, Roch].

**Principle:** increase  $p_i$  at a slower pace as  $i$  increases so as not to overtake  $p^*$  by too far:

$$p_i = \rho^{f(i)} \cdot p_0$$

where  $\rho > 1$  and  $f(i) \rightarrow \infty$  when  $i \rightarrow \infty$ ,  
but not too quickly:  $f(i)/i \rightarrow 0$  when  $i \rightarrow \infty$ .



**First example:  $f(i) = i^\alpha$  with  $0 < \alpha < 1$**

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$$\frac{T}{T^*} - 1 < 1$$

and finally

$$\frac{T}{T^*} < 2.$$



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using this lemma:  $n - 1 \sim \log_\rho p^* \cdot \log \log_\rho p^*$  as  $p^* \rightarrow \infty$ .

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Thus

$$\begin{aligned} \frac{T}{T^*} - 1 &< \frac{1}{\log(n-1)} \\ \frac{T}{T^*} &\rightarrow 1 \text{ as } n \rightarrow \infty. \end{aligned}$$

## General case

**Remaining work:** take into account the different paces in the progressions of  $p_i^*$  and  $p_j$ .



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**Remaining work:** take into account the different paces in the progressions of  $p_i^*$  and  $p_j$ .

**Idea:** one iteration using the optimal  $p_i^*$  requires several iterations using the  $p_j$ , to reach a sufficient precision.

**Recommendation:** use large  $\rho$ .

# Discussion

Large  $\rho$ ...

If  $p^*$  small and  $\rho$  large:  $p_n$  much larger than  $p^*$ .

Assumptions:  $\rho$  must be large,  $p^*$  must be large,  $p_n$  must be large and  $p_n$  should not be much larger than  $p^*$ .

**Asymptotical** result...

## Conclusion and future work

When adaptive precision is used,

- ▶ optimal overhead = 4 when computations must be restarted
- ▶ optimal overhead smaller otherwise:  
smaller than 2 with doubling precision  
asymptotically made as small as desired.

### To do:

- ▶ Detect automatically when the precision does not suffice:  
compute with current precision and doubled precision to guess  
the need of higher precision.
- ▶ Imagine incremental computations.